

Fig. 2. Concept verification setup (Mach-Zehnder interferometer configuration) to measure the generated delay. PC: polarization controller. PIN-TIA: InGaAs PIN and transimpedance amplifier.

line) is estimated as ~ 2 dB, considering the insertion losses of the circulator, PBS, and Faraday mirror. Note that the polarization-dependency of the scheme requires a well-controlled polarization state along the signal path to guarantee the desired performance.

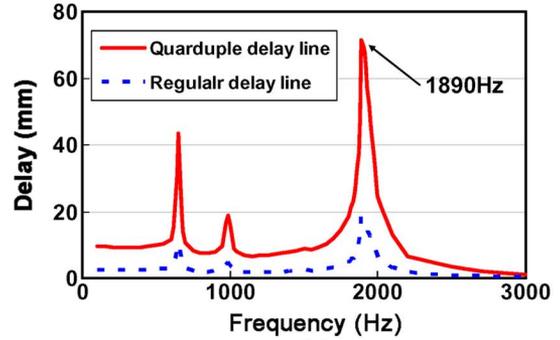
For applications where only the delay change matters, the delay fiber can be replaced with a variable delay, as shown in Fig. 1. With this configuration, any delay change is also amplified four times. All components can be enclosed in an enclosure (shown with dotted lines), except that the delay fiber or the variable delay can be placed outside the enclosure to easily change to different delays. Please note that the bandwidth of the above configuration is extremely wide, only limited by the Faraday mirror and the circulator.

III. EXPERIMENTAL VERIFICATION

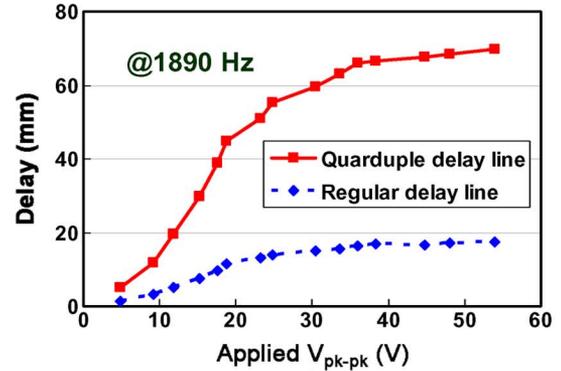
To verify the concept of the delay quadruple, we construct a Mach-Zehnder interferometer, as shown in Fig. 2. A distributed-feedback (DFB) laser at 1550 nm is first split into two paths by a 50/50 fiber coupler. The reference path contains a manual polarization controller PC1 and a reference delay line. The testing path contains a second polarization controller PC2 and a delay line under test. The two paths are then recombined by a 10/90 fiber coupler. PC1 is used to align the polarization state in the reference path to be the same as that in the testing path at the signal combining coupler and the reference delay line is used to balance the optical delay path difference between the two paths to be less than the coherence length of the DFB laser.

For TD-OCT applications, we specially design a high-speed fiber stretcher driven by a piezoelectric actuator (PZT). Such a fiber stretcher is capable of generating a delay variation of 18 mm at a resonant frequency around 2 kHz [11]. This is also the largest delay range reported at such a high frequency, a desired feature for dental OCT applications where large delay variations at high speed is required. We use this device in the experiment to verify the quadrupling concept.

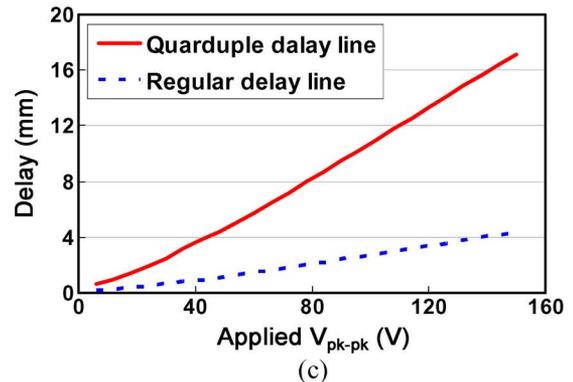
To test fast delay variations, we count interference fringes of the interferometer of Fig. 2 using a frequency counter. Each interference fringe corresponds to a delay variation of a wavelength (1550 nm in this case). In the setup, we use a sinusoidal wave signal with a frequency f_1 from a function generator to drive the fiber stretcher. The same driving signal is also used as a reference for the frequency counter. A high-speed detector is used to detect the interference signal and the output is fed into



(a)



(b)



(c)

Fig. 3. Experimental results of the delay quadrupler. (a) Delay range as a function of frequency of a fiber stretcher. The voltage applied to the PZT is 55 V. (b) Delay range as a function of applied voltage on the fiber stretcher at the resonant frequency (~ 1890 Hz). (c) Delay range as a function of applied voltage at 100 Hz. In all the graphs, the dashed line is the delay of the fiber stretcher itself and the solid line is the quadrupled delay range.

the frequency counter to measure the frequency of the interference signal. Assume that the interference signal has a frequency of f_2 , the delay range T in micrometers can be calculated as

$$T = \frac{\lambda f_2}{2f_1} = \frac{1.55f_2}{2f_1}. \quad (1)$$

We first directly insert the fiber stretcher into the setup as the “delay line under test” (Fig. 2) and measure delay variation range as a function of frequency and driving voltage. After that, we put the fiber stretcher into the delay quadrupler of Fig. 1 and insert the whole delay quadrupler into the setup as the “delay line under test” (Fig. 2) to measure delay variation range as a function of frequency and driving voltage.

The results are shown in Fig. 3(a)–(c). As can be seen, the delays are indeed increased four times for all driving frequencies

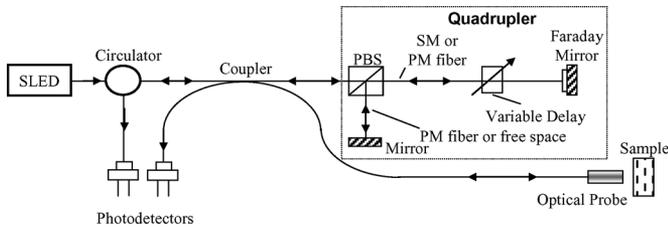


Fig. 4. Illustration of a delay quadrupler in a TD-OCT system to increase the delay variation range and the speed of the variable delay line.

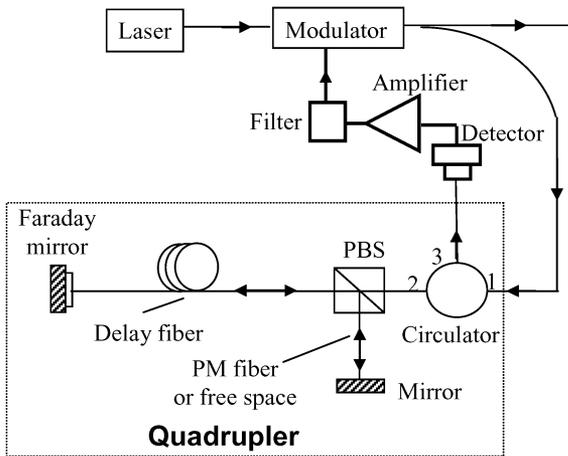


Fig. 5. Illustration of the $4\times$ delay multiplier used in an OEO application.

and driving voltages. It is important to notice that a large delay range of 72 mm is achieved at a resonant frequency of 1.89 kHz, which corresponds to a delay change rate of ~ 136 -m/s. Such a large delay range is sufficient for ophthalmic OCT application to cover the whole depth of an eye. It is also important to notice that the fiber stretcher itself without the delay quadrupler can generate a delay variation range of 18 mm at 1.89 kHz with only 55 V of applied voltage! The resonant frequency of the fiber stretcher can also be tuned to slightly above 2 kHz in the experiment. As pointed out, such a delay line is also ideal for dental OCT applications where a large delay at high frequency is required. Fig. 3(c) illustrates a generated delay at a low non-resonant frequency (i.e., 100 Hz) for applications that require better linearity but low speed.

As mentioned previously, the delay quadrupler can be used in an OCT system or a time-domain reflectometer to increase the delay range of a variable optical delay line and hence the measurement range of the system, as well as amplifying the delay variation at high speed, as shown in Fig. 4.

The delay multiplication scheme can also be used in an OEO to quadruple the total delay without increasing the fiber length, as shown in Fig. 5. In this application, not only the cost of the OEO is reduced, but also the size. Such a size reduction is of significant importance for making compact OEOs into real world applications [12].

Moreover, such a delay quadrupler can be used in dynamic optical networks, where tunable time delay lines are used as the bit stream synchronizer, optical buffers, etc. [13], [14].

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